

CS 3650 Computer Systems – Spring 2026

Processes

Week 5

Processes

Diving into the Operating Systems

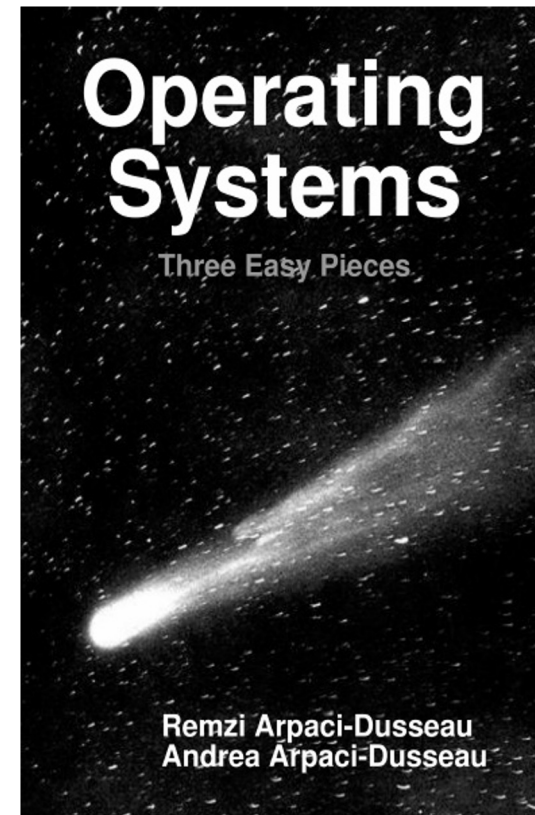
- We have been developing our knowledge of tools to prepare for the exploration of the Operating System
 - Assembly
 - C
- Today we will dive into the OS itself
- What we learned so far will be helpful understanding the OS
 - Registers and instruction concepts
 - Memory as a linear array and ways to work with memory addresses
 - C is at the core of many common OSes

OS: Virtualization + Abstraction

- The OS is a (software) land of *magic and illusions*
- OS makes a computer “easy” to use
- OS hides overwhelming complexities of hardware behind an API
 - This is **abstraction**
- OS creates the illusion of an ideal, general, and powerful machine
 - This is **virtualization**
- We will start by looking at how the processor virtualizes the CPU
- Then the process and other abstractions the OS uses

Recommended Reading

- The OSTEP book: up to Ch. 3-6
- Online: <https://pages.cs.wisc.edu/~remzi/OSTEP/>
- Hard copy: Lulu or Amazon



Running Dynamic Code

- Basic function of an OS is to execute and manage code dynamically
- For example,
 - A command issued at a command line terminal
 - An icon double clicked from the desktop
 - Jobs/tasks run as part of a batch system
- A **process** is the basic unit of a program in execution

Programs and Processes

The image shows two side-by-side windows from a Windows operating system. The left window is a File Explorer titled 'Application' showing the contents of a folder named 'Application' inside a 'Chrome' directory. It lists files like '33.0.1750.27' (File folder), '34.0.1797.2' (File folder), 'chrome.exe' (Application, 838 KB), 'master_preferences' (File, 43 KB), 'old_chrome.exe' (Application, 839 KB), and 'VersionsManifest.xml' (XML Document, 1 KB). An orange callout box points to 'chrome.exe'.

The right window is the Task Manager, showing the 'Processes' tab. It lists running processes with columns for Name, PID, Status, Session Name, Session ID, Private Bytes, and Description. Multiple instances of 'chrome.exe' are listed, each with a different PID (e.g., 4924, 5412, 5480, 5808, 5860, 6036, 2224, 5004, 5300, 4200, 2220, 4188, 6360, 5100, 6780, 6956, 8144, 6436). Other processes like 'CommonAgent.exe', 'conhost.exe', and 'csrss.exe' are also visible. An orange callout box points to the 'chrome.exe' entries.

Program
An executable file in long-term storage

Process
The running instantiation of a program, stored in RAM

One-to-many relationship between program and processes

How to Run a Program?

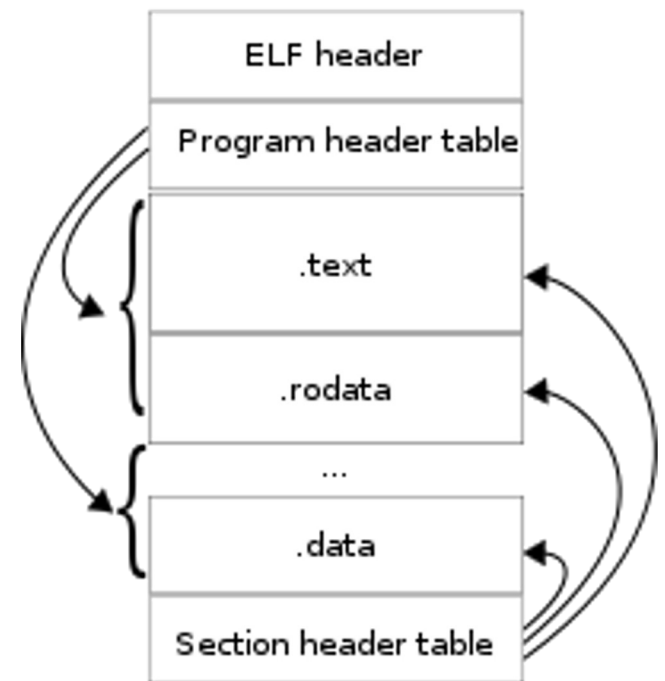
- How does the OS turn a double-clicked executable file into a process?
- What information must the executable file contain to run as a program?

Program Formats

- Programs obey specific file formats
 - CP/M (control program monitor) and DOS (disk operating system) : COM executables (*.com)
 - DOS: MZ executables (*.exe)
 - Named after Mark Zbikowski, a DOS developer
 - Windows Portable Executable (PE, PE32+) (*.exe)
 - Modified version of Unix COFF executable format
 - PE files start with an MZ header.
 - Unix/Linux: Executable and Linkable Format (ELF)
 - Mac OSX: Mach object file format (Mach-O)

ELF File Format

- Spec: <https://refspecs.linuxfoundation.org/elf/elf.pdf>
- ELF Header
 - Contains compatibility info
 - Entry point of the executable code
- Program header table
 - Lists all the segments in the file
 - Used to load and execute the program
- Section header table
 - Used by the linker

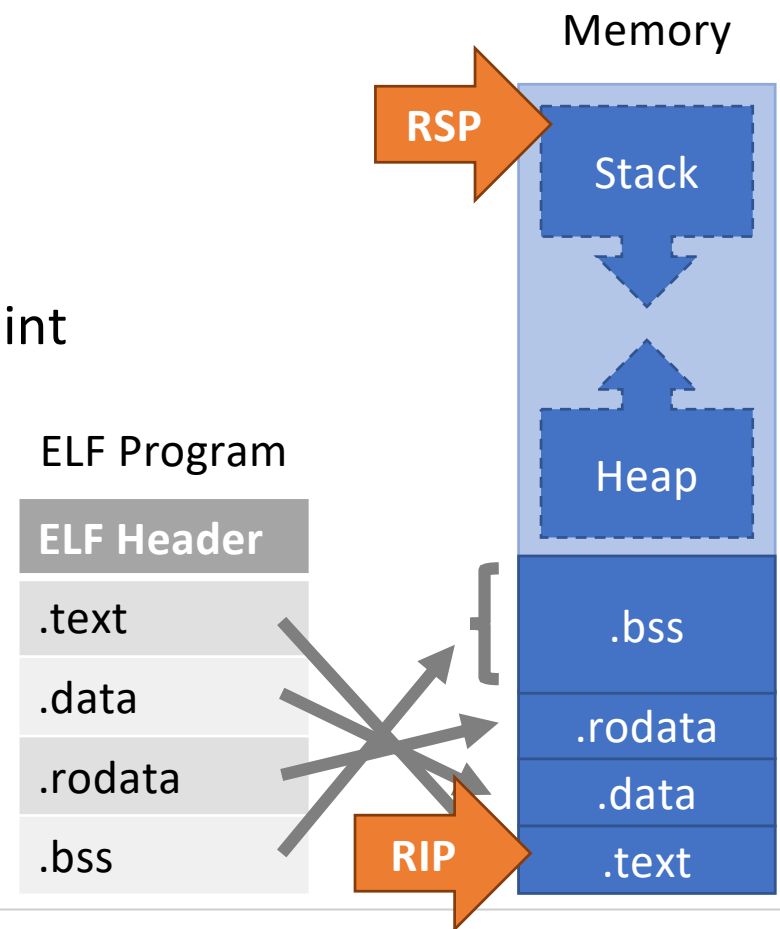


ELF Header Example

```
$ gcc -g -o test test.c
$ readelf --header test
ELF Header:
Magic:      7f 45 4c 46 02 01 01 00 00 00 00 00 00 00 00
Class:      ELF64
Data:      2's complement, little endian
Version:    1 (current)
OS/ABI:     UNIX - System V
ABI Version: 0
Type:      EXEC (Executable file)
Machine:    Advanced Micro Devices X86-64
Version:    0x1
Entry point address: 0x400460
Start of program headers: 64 (bytes into file)
Start of section headers: 5216 (bytes into file)
Flags:      0x0
Size of this header: 64 (bytes)
Size of program headers: 56 (bytes)
Number of program headers: 9
Size of section headers: 64 (bytes)
Number of section headers: 36
Section header string table index: 33
```

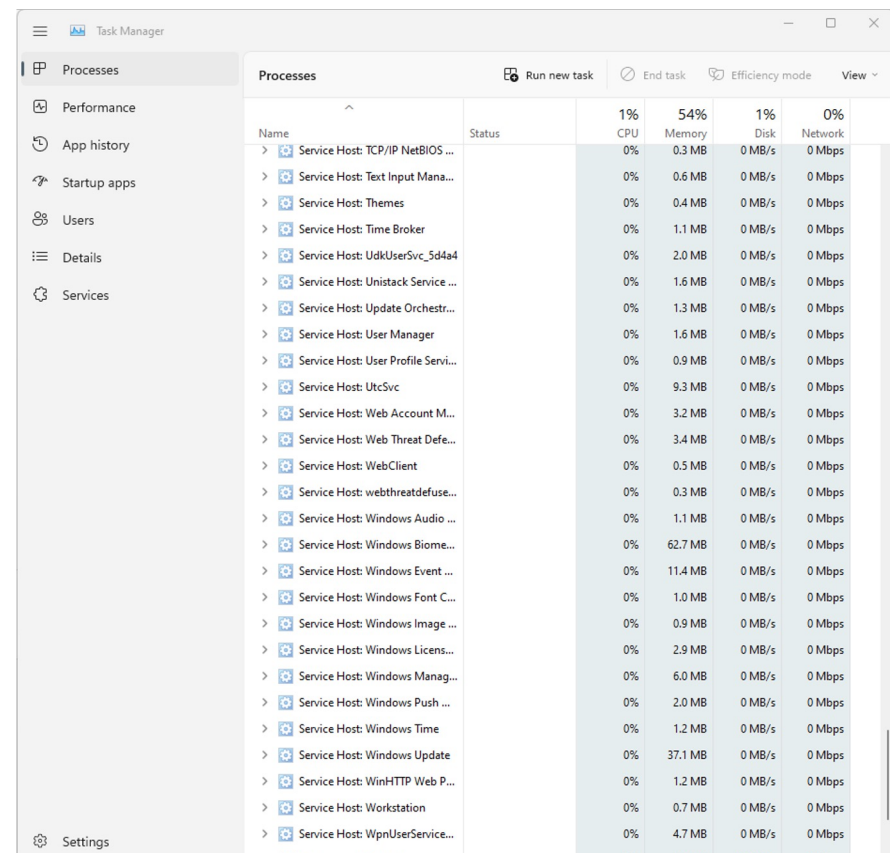
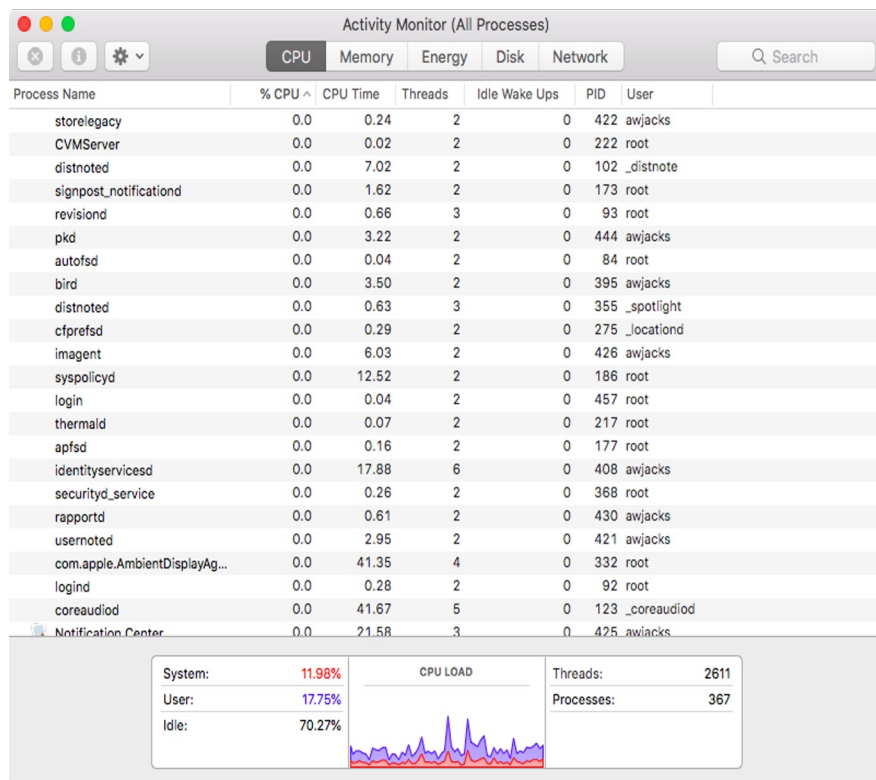
The Program Loader

- OS functionality that loads programs into memory, creates processes
 - Places segments into memory
 - Loads necessary dynamic libraries
 - Performs relocation
 - Allocated the initial stack frame
 - Sets EIP/RIP to the program's entry point
- Process is a live program execution context or basic unit of execution



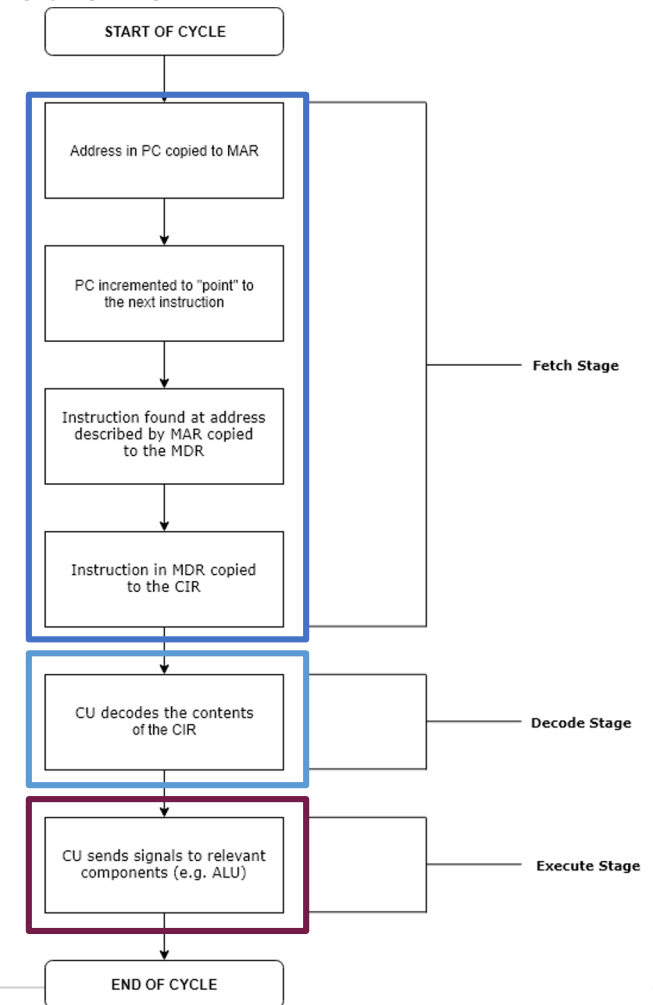
Warmup

- How many processes do you have open at any given time?
 - 10s, 100s? More!? :)



First: Instruction Execution

- Code in an executable is a sequence of instructions
- CPU runs an instruction at a time
- This is done in a **fetch-decode-execute** cycle
- If you have **4 cores**, your processor can do **4 FDE cycles** at a time
- But how do we see ~100s of programs running on 4 cores?
- What about a single core CPU?



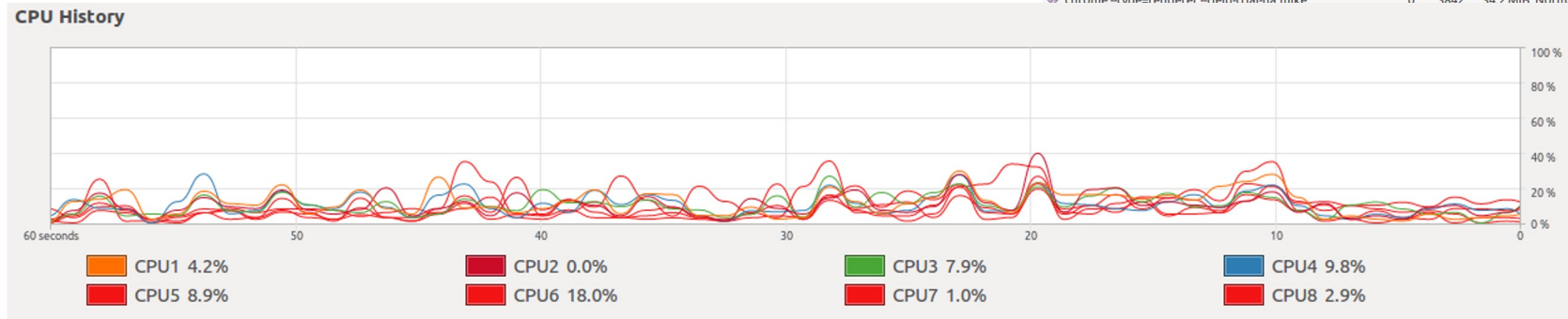
MAR: holds address of current instruction, MDR: holds contents of address in MAR
CIR: stores current instruction, so not overwritten by additional fetches to MBR/MDR

From the warm up

- Many programs are running, but only 8 CPUs that do the work

The Problem: So how does our Operating System provide the illusion of 100s of processes running at once?

System Monitor						
			Processes		Resources	File Systems
Process Name	User	% CPU	ID	Memory	Priority	
at-spi2-registr...	mike	0	2322	472.0 KiB	Normal	
at-spi-bus-lau...	mike	0	2313	460.0 KiB	Normal	
bamfdamon	mike	0	2335	6.2 MiB	Normal	
cat	mike	0	2972	68.0 KiB	Normal	
cat	mike	0	2973	64.0 KiB	Normal	
chrome	mike	0	2965	131.5 MiB	Normal	
chrome-type=...	mike	0	3045	11.0 MiB	Normal	
chrome-type=...	mike	0	3043	71.2 MiB	Normal	
chrome-type=...	mike	0	9930	14.2 MiB	Normal	
chrome-type=...	mike	0	7595	383.3 MiB	Normal	
chrome-type=...	mike	0	9875	33.2 MiB	Normal	
chrome-type=...	mike	0	6739	58.3 MiB	Normal	
chrome-type=...	mike	0	7748	359.9 MiB	Normal	
chrome-type=...	mike	0	3163	251.6 MiB	Normal	
chrome-type=...	mike	0	6804	291.8 MiB	Normal	
chrome-type=...	mike	0	3197	16.7 MiB	Normal	
chrome-type=...	mike	0	3641	39.5 MiB	Normal	
chrome-type=...	mike	0	9435	207.7 MiB	Normal	
chrome-type=...	mike	0	7056	337.0 MiB	Normal	
chrome-type=...	mike	0	3778	54.6 MiB	Normal	
chrome-type=...	mike	0	3950	59.4 MiB	Normal	
chrome-type=...	mike	0	8845	129.4 MiB	Normal	
chrome-type=...	mike	0	3740	39.7 MiB	Normal	
chrome-type=...	mike	0	3578	56.5 MiB	Normal	
chrome-type=...	mike	0	3833	37.4 MiB	Normal	
chrome-type=...	mike	0	8927	340.0 MiB	Normal	
chrome-type=...	mike	0	3965	55.0 MiB	Normal	
chrome-type=...	mike	0	3842	34.2 MiB	Normal	



Virtualization with time sharing

- The Operating System (OS) runs one process at a time,
 - That executes one instruction a time
 - After some amount of time the process stops or finishes
 - Then the OS starts another process
 - Eventually the same process will run again and continue where it left off
 - Repeat

Time	Process ₀	Process ₁	Notes
1	Running	Ready	
2	Running	Ready	
3	Running	Ready	
4	Running	Ready	Process ₀ now done
5	–	Running	
6	–	Running	
7	–	Running	
8	–	Running	Process ₁ now done

- This concept is known as time sharing
- Are the two states, **Running** and **Ready**, enough?

Process States

- What if the process needs to read/write to disk or perform a network request? Any problems?
 - These operations take (comparatively) long to complete
 - Keeping process state to **Running**?
 - Hogs the CPU just waiting for disk/network access to complete
 - Keeping process state to **Ready**?
 - Might not be ready to run when its turn comes
 - Asking it to run may be waste of time
- Solution?
 - Introduce a 3rd state, **Blocked**
 - Meaning: the process requested some I/O operation and cannot run until that operation is completed

Process States

- Each process can be in one of several states
- The OS schedules the state the process is in
- Typically, these are:
 - Running: the process is executing on the CPU
 - Ready: the process is ready to execute, but the OS did not choose to run it
 - Blocked - the process issued some blocking operation
 - I/O is a common blocking operation

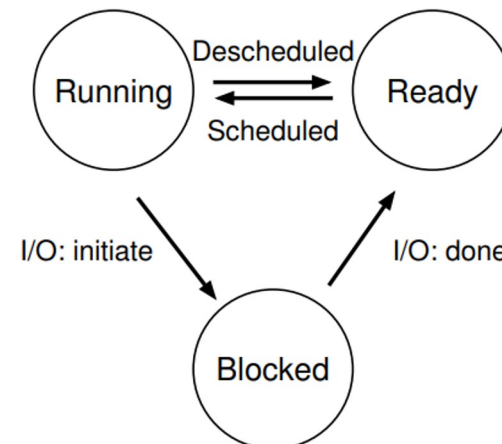


Figure 4.2: Process: State Transitions

Then how does OS switch processes?

OS Challenges to Virtualization

- Performance
 - How to implement virtualization without excessive overhead
- Control
 - How to run multiple processes without losing control over the CPU?
 - Without OS control, a process
 - could occupy the CPU and run forever
 - access memory it does not have access impacting safety and security

Switching between processes

- Switching between processes is a challenge, because

If the CPU is running a program, then the OS is not running

- If OS is not running, then how can it switch out/in processes?
 - Think about how you would design the OS!

When Do You Switch Processes?

- To share CPU between multiple processes, control must eventually return to the OS
 - When should this happen?
 - What mechanisms implements the switch from user process back to the OS?
- Four approaches:
 1. Voluntary yielding
 2. Switch during API calls to the OS
 3. Switch on I/O
 4. Switch based on a timer interrupt

Voluntary Yielding

- Idea: processes must voluntarily give up control by calling an OS API, e.g. `thread_yield()`
- Problems?
 - Misbehaving or buggy apps may never yield
e.g., `while (1) { //do something without yielding }`
 - No guarantee that apps will yield in a reasonable amount of time
 - Waste of CPU resources, i.e. what if a process is idle-waiting on I/O?

Interjection on OS APIs

- Idea: whenever a process calls an OS API, this gives the OS an opportunity to context switch
 - E.g. `printf()`, `fopen()`, `socket()`, etc...
- The original Apple Macintosh used this approach
 - Cooperative multi-tasking
- Problems?
 - Misbehaving or buggy apps may never yield
 - Some normal apps don't use OS APIs for long periods of time
 - E.g. a long, CPU intensive matrix calculation

Switching on I/O

- Idea: when one process is waiting on I/O, switch to another process
 - I/O APIs already go through the OS, so context switching is easy
- Problems?
 - Some apps don't have any I/O for long periods of time

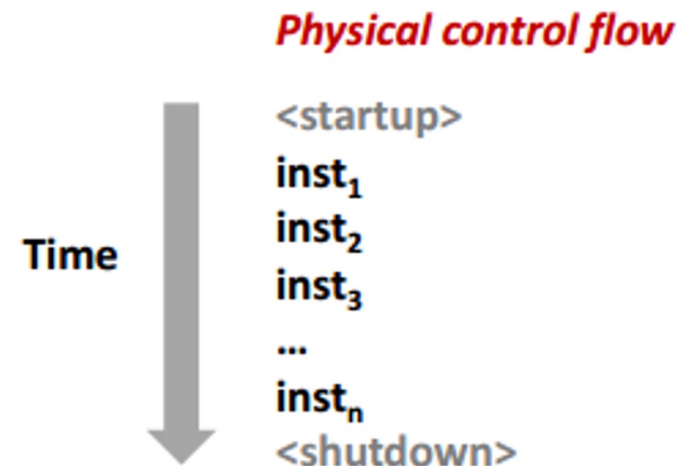
Preemptive Switching

- So far, processes will not switch to another until an action is taken
 - e.g. an API call or an I/O interrupt
- Idea: use a timer to force context switching at set intervals
 - Timer is running at a fixed frequency to measure how long a process has been running
 - If it's been running for some max duration (scheduling quantum), the handler switches to the next process
- Problems? Who will trigger the timer
 - Requires hardware support (a programmable timer)
 - Thankfully, this is built-in to most modern CPUs

Mechanisms for switching: Exceptional Control Flow

Remember

- Computers only really do one thing; they execute one instruction one after another
 - Based on the order of instructions executing in your program.
 - Your programs follow some control flow based on jumps and branches (and calls and returns)
 - This is based on your programs state.



- However, sometimes we want to react based on the system state
 - E.g., you hit Ctrl+C on the keyboard in your terminal and execution stops.

Exceptional Control Flow Mechanisms

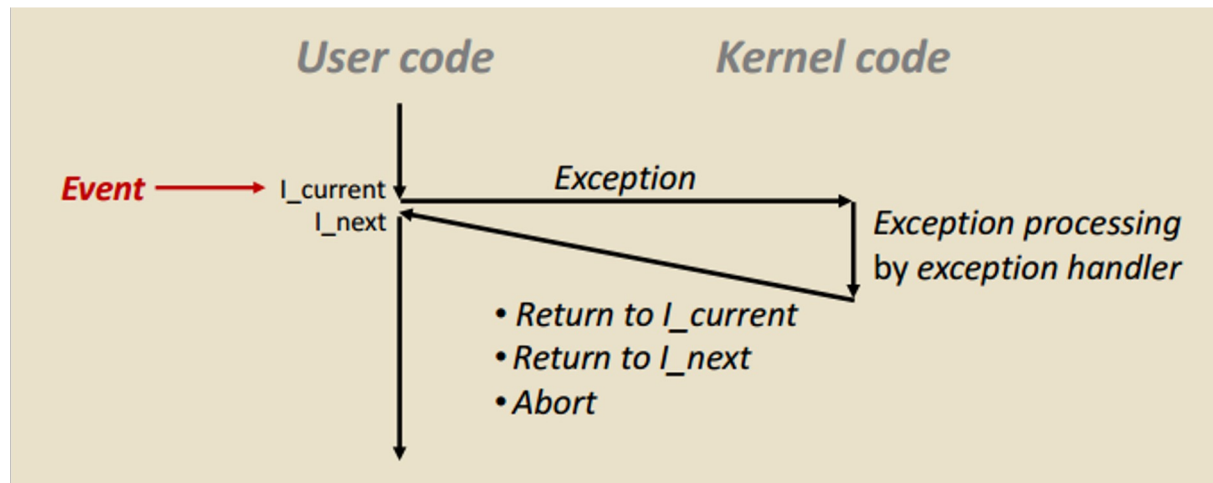
- Low level mechanism
 - Exceptions
 - Change in control flow in response to a system event.
 - This is implemented in hardware and OS software

Exceptional Control Flow Mechanisms

- High level mechanisms
 - Process context switch
 - e.g. It appears that multiple programs are running at once on your OS, but remember only one instruction at a time.
 - Context switches provide this illusion
 - Signals
 - Implemented by OS software

Exceptions

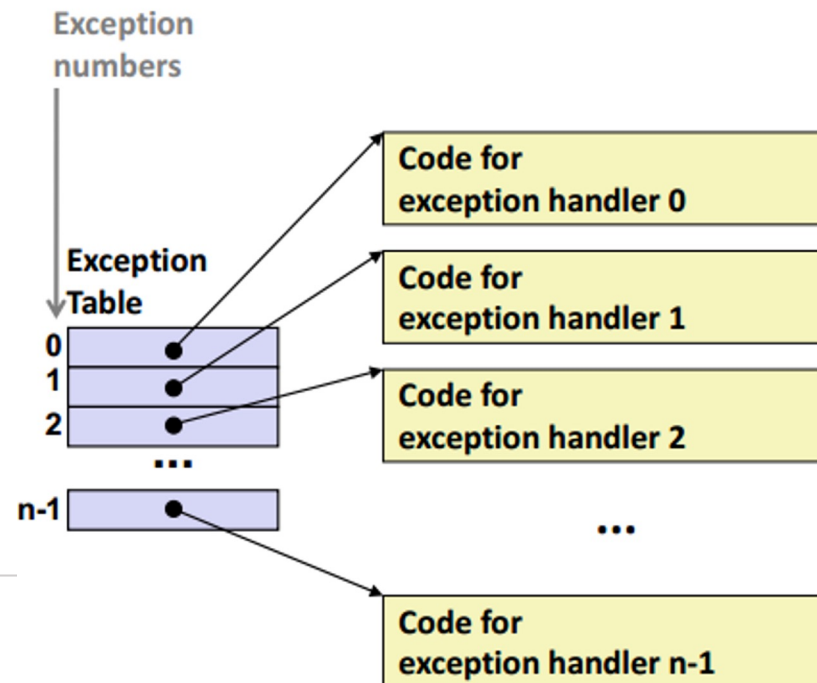
- An exception is a transfer of control to the OS kernel
 - The kernel is the memory-resident part of the OS
 - Meaning OS lives in memory forever: we do not modify this!
- Examples of exceptions we may be familiar with:
 - Divide by 0, arithmetic overflow, or typing Ctrl+C



- How does the OS know how to handle the exception?

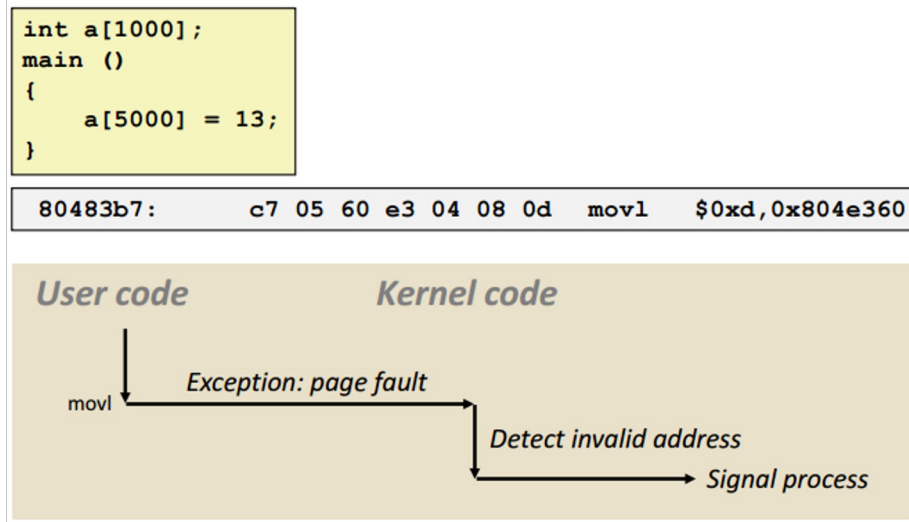
Exception Tables

- Somewhere in the OS, a table exists with different exceptions.
 - Think of it like a giant switch or many if else-if statements.
- This is part of a kernel that you cannot modify.
 - This code is in a “**protected region**” of memory
- For each exception, there is one way to handle it (i.e., “**exception handlers**”)

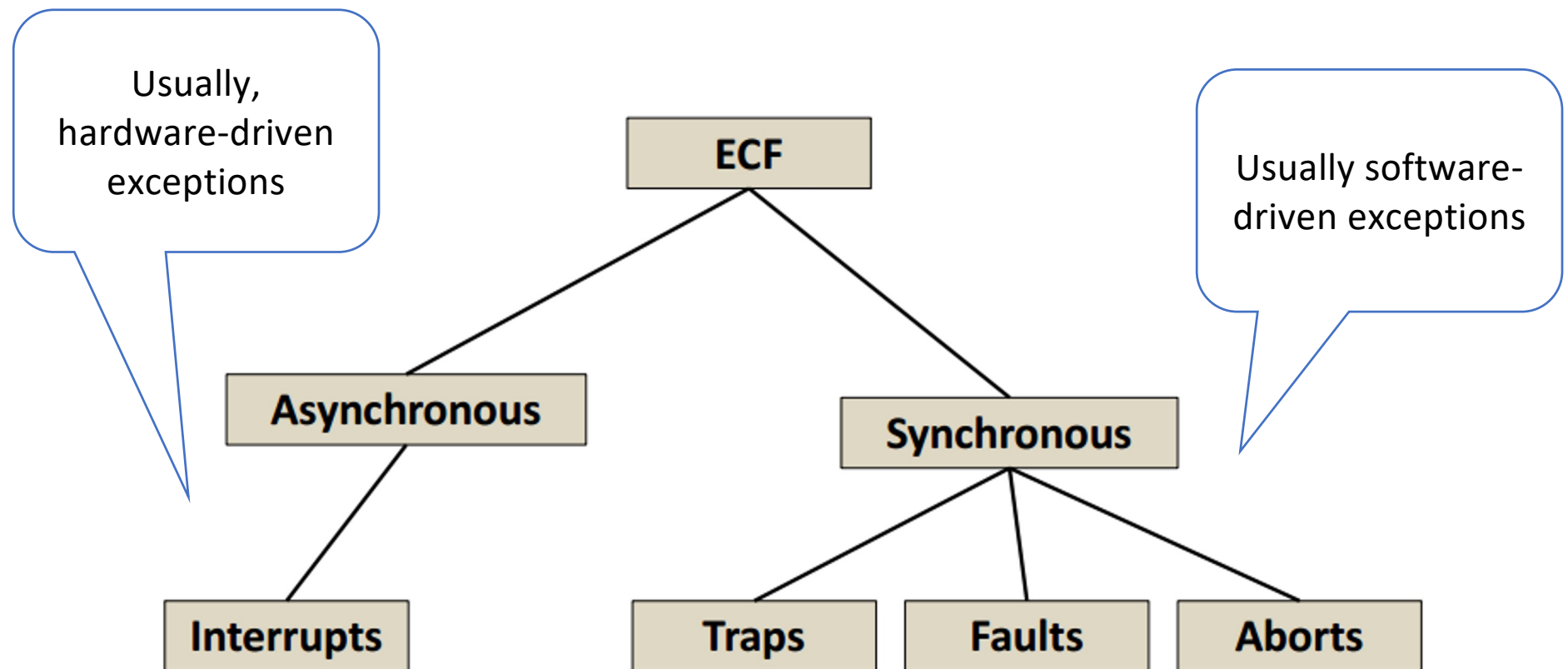


Our favorite: Invalid Memory Reference

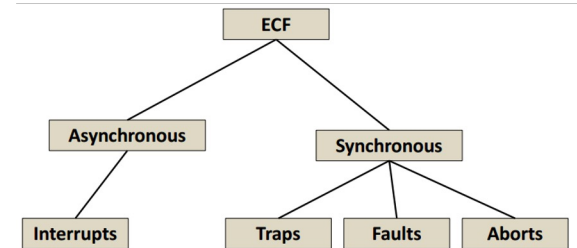
- That is, the segmentation fault
 - OS sends signal SIGSEGV to our user process
 - This time the program gets terminated.



Exceptional Control Flow Taxonomy



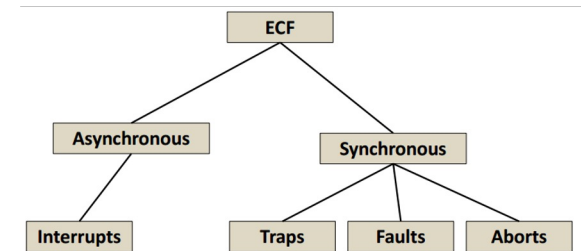
Asynchronous Exceptions (Interrupts)



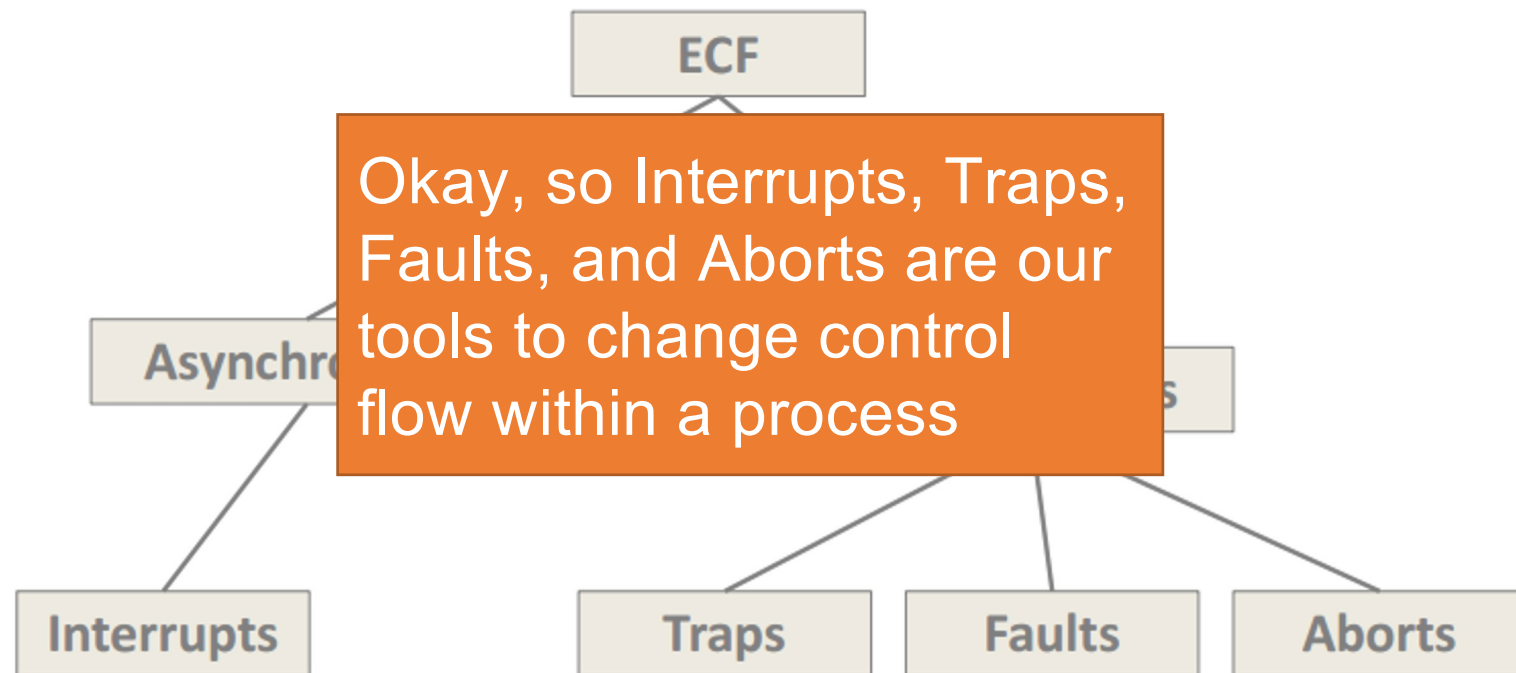
- Caused by events external to processor
 - I.e., not from the result of an instruction the user wrote
 - E.g.
 - Timer interrupts scheduled to happen every few milliseconds
 - A kernel can use this to take back control from a program/user
 - Some network data arrives (I/O)
 - A nice example is while reading from disk
 - The processor can start reading, then hop over and perform some other tasks until memory is actually fetched.

Synchronous Exceptions

- Events caused by executing an instruction
 - Traps
 - Intentionally done by the user
 - e.g. system calls, breakpoints (like in gdb)
 - Returns control to the next instruction
 - Faults
 - Unintentional, but possibly recoverable
 - e.g. [page faults](#) (we'll learn more about soon), floating point exceptions
 - Handled by re-executing current instruction or aborting execution
 - Aborts
 - Unintentional and unrecoverable
 - e.g. illegal instruction executed, [parity error](#)



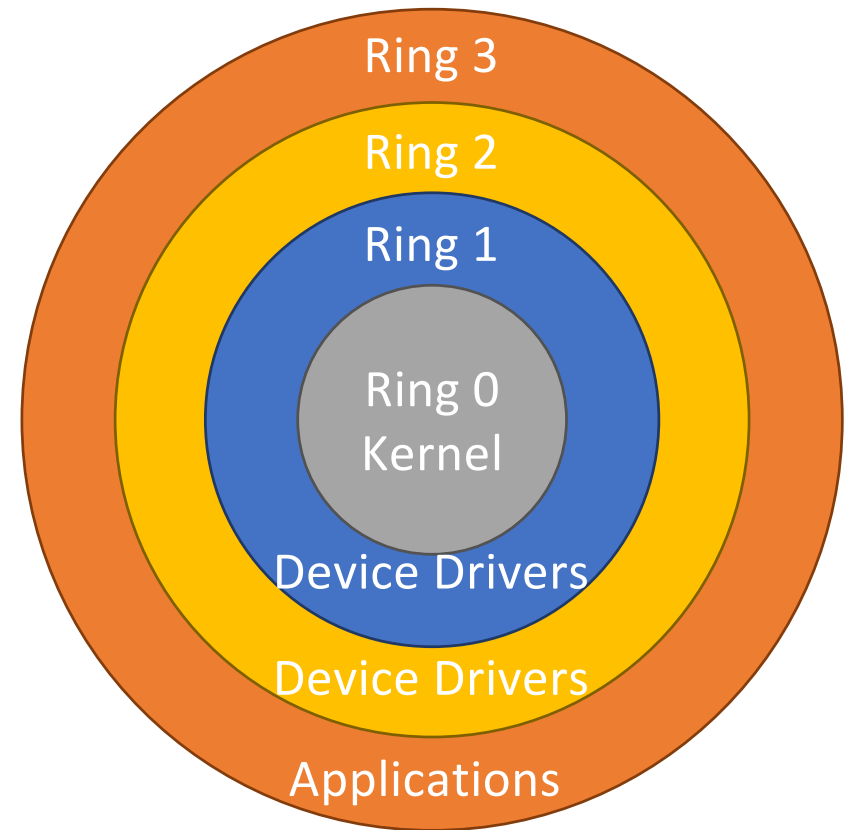
Exceptional Control Flow Taxonomy



System calls

Different privilege levels

- Most modern CPUs support protected mode
- x86 CPUs support three rings with different privileges
 - Ring 0: OS kernel
 - Ring 1, 2: device drivers
 - Ring 3: userland
- Most OSes only use rings 0 and 3



Dual-Mode Operation

- Ring 0: kernel/supervisor mode
 - Execution with the full privileges of the hardware
 - Read/write to any memory, access any I/O device, read/write any disk sector, send/read any packet
- Ring 3: user mode or “userland”
 - Limited privileges
 - Only those granted by the operating system kernel

Protected Features

- What system features are impacted by protection?
 - Privileged instructions
 - Only available to the kernel
 - Limits on memory accesses
 - Prevents user code from overwriting the kernel
 - Access to hardware
 - Only the kernel may directly interact with peripherals
 - Programmable Timer Interrupt
 - May only be set by the kernel
 - Used to force context switches between processes

System Calls

- Syscall is the lowest level of interaction with an operating system from a C programmer
- A user program can ask the OS for services that the OS manages
 - You may have used ‘_exit’ in your assignment
 - Anything else you can think of?

<i>Number</i>	<i>Name</i>	<i>Description</i>
0	read	Read file
1	write	Write file
2	open	Open file
3	close	Close file
4	stat	Get info about file
57	fork	Create process
59	execve	Execute a program
60	_exit	Terminate process
62	kill	Send signal to process

Changing Modes

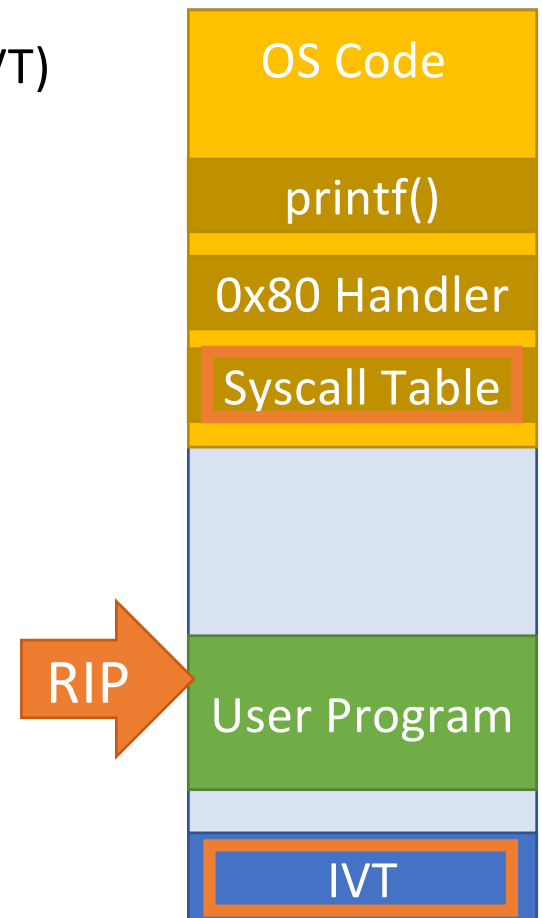
- Applications often need to access the OS
 - i.e. system calls
 - Writing files, displaying on the screen, receiving data from the network, etc...
- But the OS is ring 0, and apps are ring 3
- How do apps get access to the OS?
 - Apps invoke system calls with an interrupt
 - E.g. int 0x80
 - **int** causes a mode transfer from ring 3 to ring 0

System Call Example

Note: this shows a physical memory layout. The user program thinks it owns the entire memory space (the diagram that we saw in previous lectures).

1. Software executes `int 0x80`
 - Pushes E/RIP, CS, and EFLAGS
2. CPU transfers execution to the OS handler
 - Look up the handler in the Interrupt Vector Table (IVT)
 - Switch from ring 3 to 0
3. OS executes the system call
 - Save the processes state
 - Use E/RAX to locate the system call
 - Execute the system call
 - Restore the processes state
 - Put the return value in E/RAX
4. Return to the process with `iret`
 - Pops E/RIP, CS, and EFLAGS
 - Switches from ring 0 to 3

Physical Main Memory



System Calls and arguments

- Helpful webpage with syscalls and arguments
 - <https://filippo.io/linux-syscall-table/>

8	lseek	sys_lseek	fs/read_write.c
9	mmap	sys_mmap	arch/x86/kernel/sys_x86_64.c
10	mprotect	sys_mprotect	mm/mprotect.c
11	munmap	sys_munmap	mm/mmap.c
12	brk	sys_brk	mm/mmap.c

%rdi

unsigned long brk

Opening a File

- rax holds the system call # that we want to pass.
 - Other arguments accessed as follows

%rax	Name	Entry point	Implementation
0	read	sys_read	fs/read_write.c
1	write	sys_write	fs/read_write.c
2	open	sys_open	fs/open.c

%rdi	%rsi	%rdx
const char __user * filename	int flags	umode_t mode

Opening a File | Illustration

0000000000e5d70 <__open>:

...

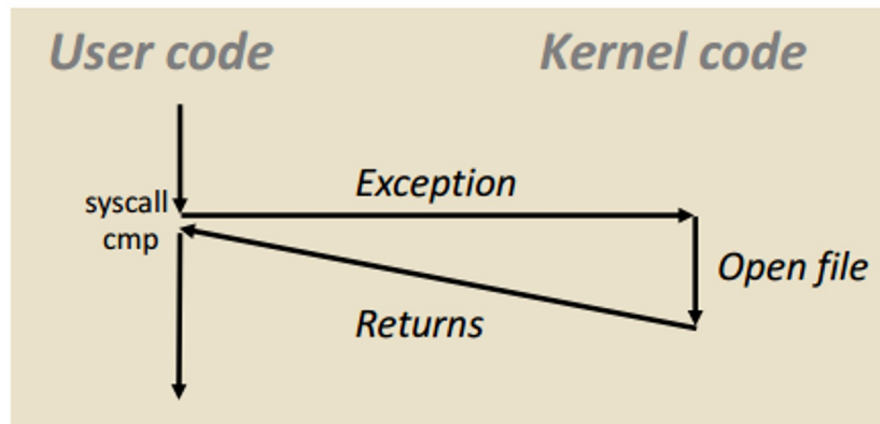
e5d79: b8 02 00 00 00 mov \$0x2,%eax # open is syscall #2

e5d7e: 0f 05 syscall # Return value in %rax

e5d80: 48 3d 01 f0 ff ff cmp \$0xffffffffffff001,%rax

...

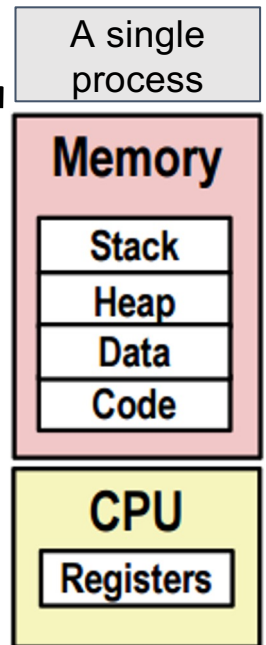
e5dfa: c3 retq



Processes
STOP HERE

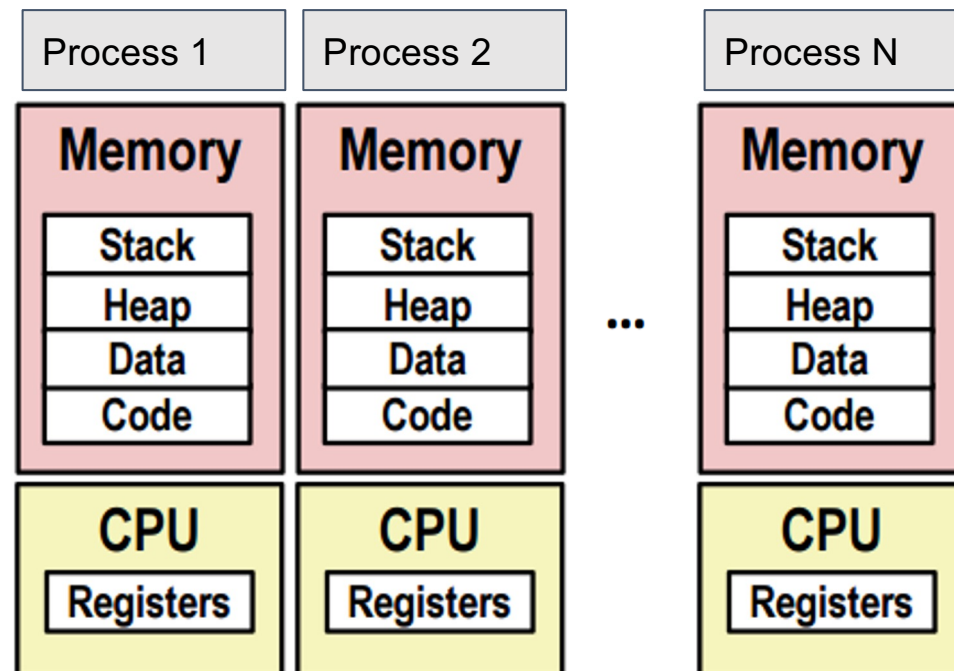
The Process

- A process is alive, a program is dead. Long live the process!
 - (A program is just the code.)
- Processes are organized by the OS using two key abstractions
 - Logical Control Flow
 - Programs “appear” to have exclusive control over the CPU
 - Done by “context switching”
 - Private Address Space
 - Each program “appears” to have exclusive use of main memory
 - Provided by mechanism called virtual memory



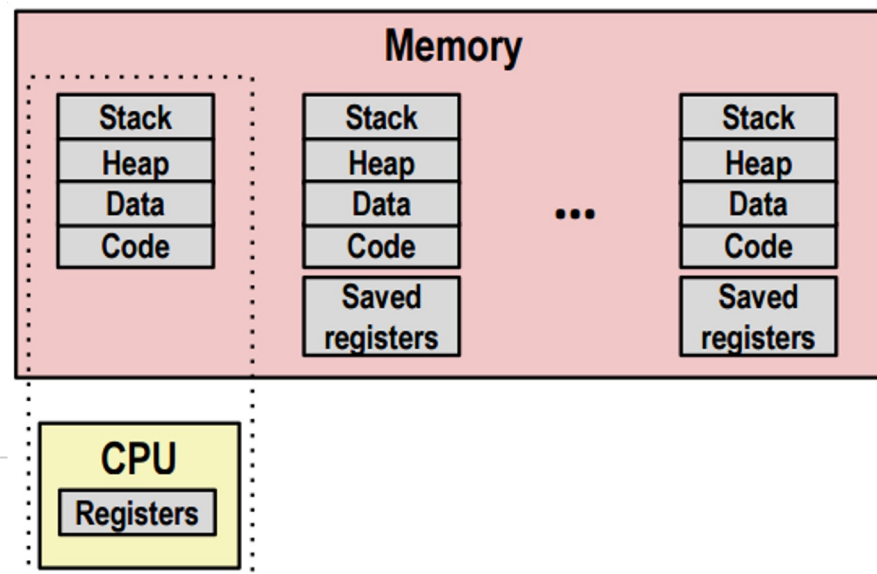
Multiprocessing: Illusion

- When running processes, it appears that we are running many different tasks at the same time
- It also appears that our memory is neatly organized.
 - Note from this diagram we see every process has its own
 - stack
 - heap
 - data
 - code
 - registers

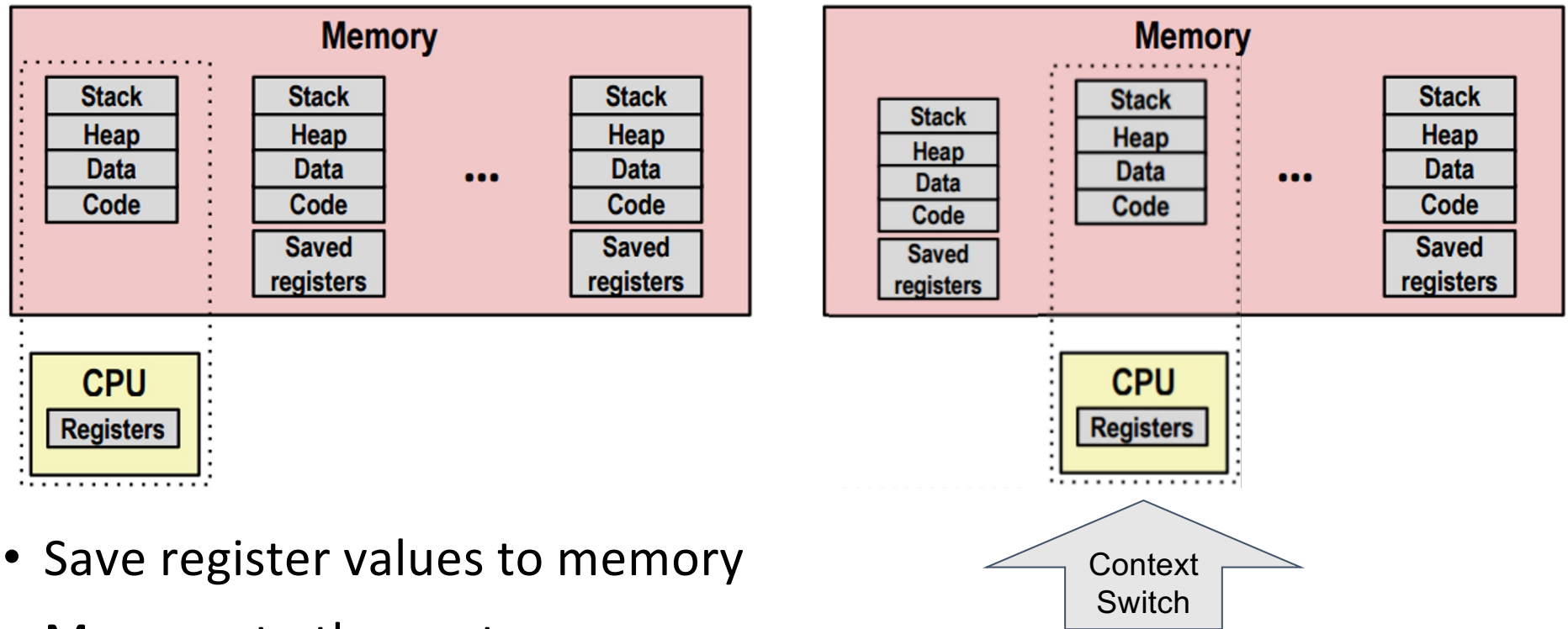


Multiprocessing: Reality

- Remember, at any time, only one processor is really running code
- Program execution is interleaved
- OS manages memory addresses in **virtual memory**
- OS stores the saved registers for different programs.
 - (At some point in this class, you probably figured 16 registers is not enough for all of the processes that you were running.)
- When we switch which process is executing: **this is a context switch**



Context switch: a high-level view



- Save register values to memory
- Move on to the next process
 - Point to the stack of the next process
 - Restore saved register values
- Start running executing the next process

Storing Register Context | Data Structures

- In order to store the state of the registers, your OS will keep track of this information
- Typically there is a process list, and the list contains information like the registers.
- To the right is a *struct* for the xv6 operating system storing 32-bit registers. *We will use xv6 later in the semester.*

```
// the registers xv6 will save and restore
// to stop and subsequently restart a process
struct context {
    int eip;
    int esp;
    int ebx;
    int ecx;
    int edx;
    int esi;
    int edi;
    int ebp;
};
```

Storing Process Information | Data Structures

- Additional information such as the process state is stored by the OS.
- **proc** is the data structure which stores information about each process (linux uses `task_struct`)
- To the right is the `struct proc` for the xv6 operating system

```
// the different states a process can be in
enum proc_state { UNUSED, EMBRYO, SLEEPING,
                  RUNNABLE, RUNNING, ZOMBIE };

// the information xv6 tracks about each process
// including its register context and state
struct proc {
    char *mem;                // Start of process memory
    uint sz;                  // Size of process memory
    char *kstack;             // Bottom of kernel stack
                              // for this process
    enum proc_state state;    // Process state
    int pid;                  // Process ID
    struct proc *parent;      // Parent process
    void *chan;               // If non-zero, sleeping on chan
    int killed;               // If non-zero, have been killed
    struct file *ofile[NOFILE]; // Open files
    struct inode *cwd;         // Current directory
    struct context context;    // Switch here to run process
    struct trapframe *tf;      // Trap frame for the
                              // current interrupt
};
```

Storing Process Information | Data Structures

- According to the OS, such as

Process state

such as

Process id

which stores information about each process (linux uses

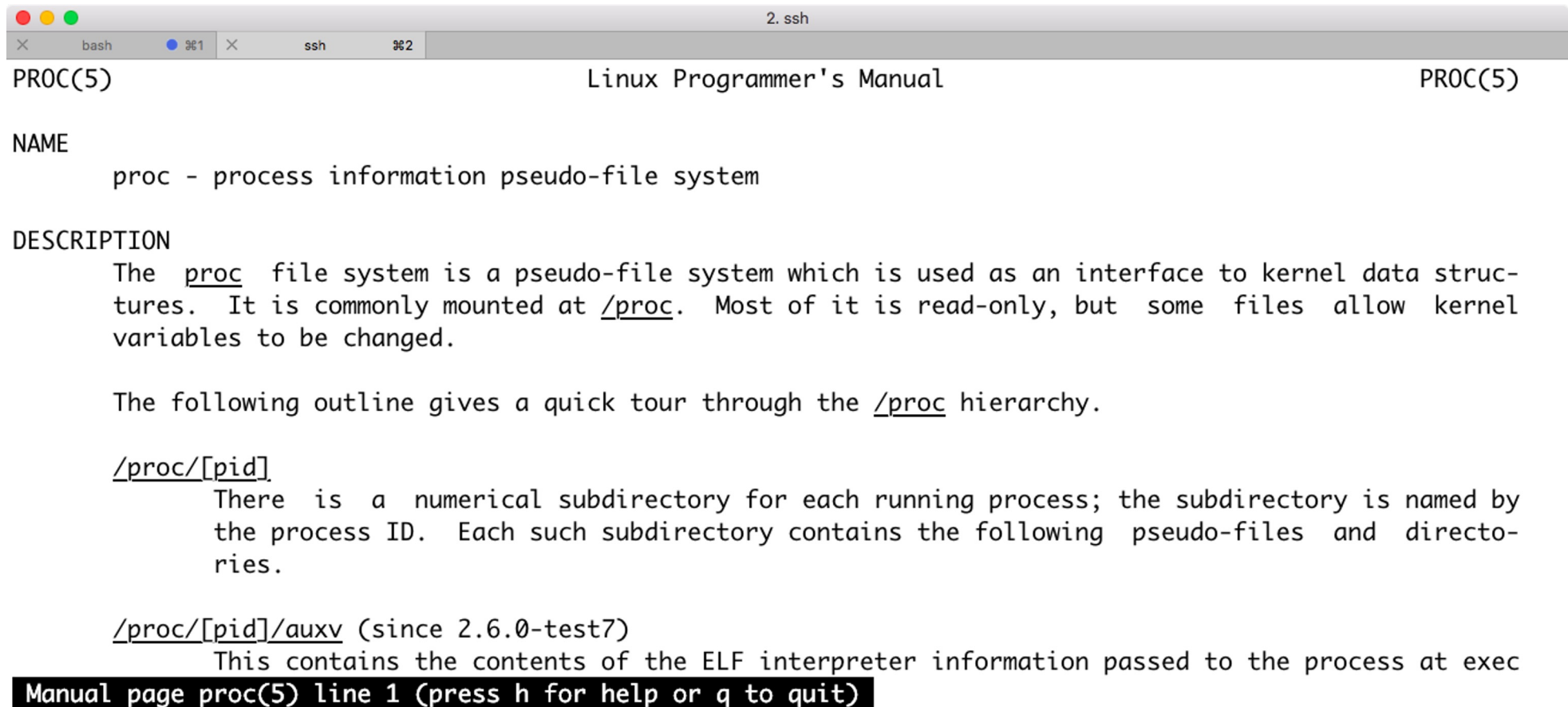
Registers that we saw earlier

- To the right is the struct proc for the xv6 operating system

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    uint sz;                  // Size of process memory
    char *kstack;             // Bottom of kernel stack
                              // for this process
    enum proc_state state;    // Process state
    int pid;                  // Process ID
    struct proc *parent;      // Parent process
    void *chan;               // If non-zero, sleeping on chan
    int killed;               // If non-zero, have been killed
    struct file *ofile[NOFILE]; // Open files
    struct inode *cwd;         // Current directory
    struct context context;    // Switch here to run process
    struct trapframe *tf;     // Trap frame for the
                              // current interrupt
};
```

man proc



The screenshot shows a terminal window titled "2. ssh" with two tabs: "bash" and "ssh". The terminal displays the output of the command `man proc`. The header of the man page reads "PROC(5) Linux Programmer's Manual PROC(5)". The "NAME" section states: "proc - process information pseudo-file system". The "DESCRIPTION" section explains that the `proc` file system is a pseudo-file system used as an interface to kernel data structures, commonly mounted at `/proc`. It notes that most files are read-only, but some allow kernel variables to be changed. It then provides an outline of the `/proc` hierarchy, starting with `/proc/[pid]`, where `[pid]` is a numerical subdirectory for each running process. It also mentions `/proc/[pid]/auxv` (since 2.6.0-test7) and states that it contains ELF interpreter information passed to the process at execution. At the bottom, a black bar contains the text "Manual page proc(5) line 1 (press h for help or q to quit)".

```
PROC(5)                                Linux Programmer's Manual                                PROC(5)

NAME
    proc - process information pseudo-file system

DESCRIPTION
    The proc file system is a pseudo-file system which is used as an interface to kernel data structures. It is commonly mounted at /proc. Most of it is read-only, but some files allow kernel variables to be changed.

    The following outline gives a quick tour through the /proc hierarchy.

    /proc/[pid]
        There is a numerical subdirectory for each running process; the subdirectory is named by the process ID. Each such subdirectory contains the following pseudo-files and directories.

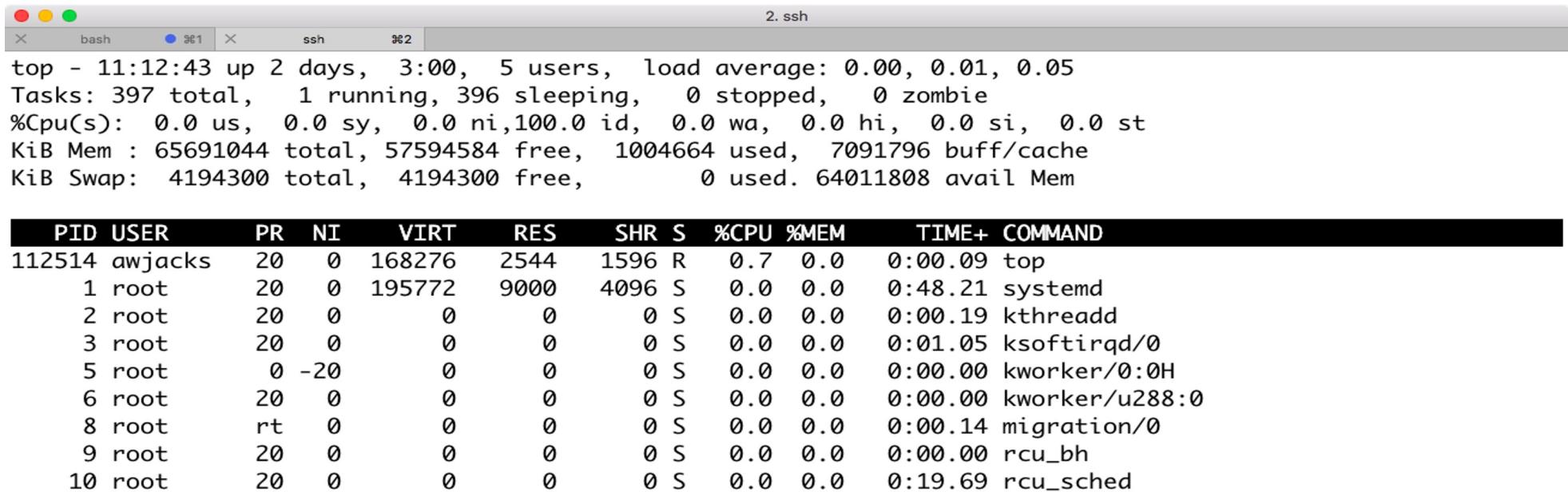
    /proc/[pid]/auxv (since 2.6.0-test7)
        This contains the contents of the ELF interpreter information passed to the process at exec

Manual page proc(5) line 1 (press h for help or q to quit)
```

top

```
TOP(1) User Commands
NAME
top - display Linux processes
```

- top is a program that will show linux processes that are running
 - Top shows all of the processes running on a system
 - Intuitively, it must be possible for a machine to host multiple processes, we do so when we ssh.



```
top - 11:12:43 up 2 days, 3:00, 5 users, load average: 0.00, 0.01, 0.05
Tasks: 397 total, 1 running, 396 sleeping, 0 stopped, 0 zombie
%Cpu(s): 0.0 us, 0.0 sy, 0.0 ni,100.0 id, 0.0 wa, 0.0 hi, 0.0 si, 0.0 st
KiB Mem : 65691044 total, 57594584 free, 1004664 used, 7091796 buff/cache
KiB Swap: 4194300 total, 4194300 free, 0 used. 64011808 avail Mem
```

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TIME+	COMMAND
112514	awjacks	20	0	168276	2544	1596	R	0.7	0.0	0:00.09	top
1	root	20	0	195772	9000	4096	S	0.0	0.0	0:48.21	systemd
2	root	20	0	0	0	0	S	0.0	0.0	0:00.19	kthreadd
3	root	20	0	0	0	0	S	0.0	0.0	0:01.05	ksoftirqd/0
5	root	0	-20	0	0	0	S	0.0	0.0	0:00.00	kworker/0:0H
6	root	20	0	0	0	0	S	0.0	0.0	0:00.00	kworker/u288:0
8	root	rt	0	0	0	0	S	0.0	0.0	0:00.14	migration/0
9	root	20	0	0	0	0	S	0.0	0.0	0:00.00	rcu_bh
10	root	20	0	0	0	0	S	0.0	0.0	0:19.69	rcu_sched

htop

HTOP(1)

NAME

htop - interactive process viewer

- htop is another program to show running processes
 - It shows cores and their load
 - It also shows the process tree (process / subprocess relationships)
 - It can be scrolled left/right and up/down

```

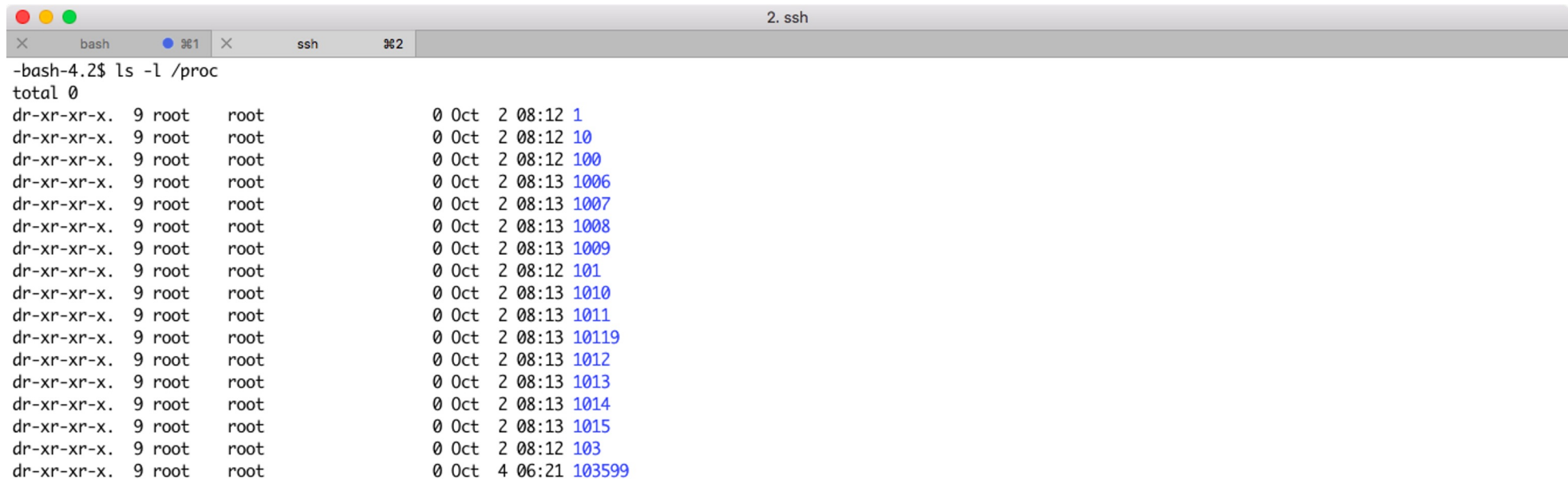
1.12G/62.6G Tasks: 66, 53 thr; 1 running
0K/4.00G Load average: 0.00 0.01 0.05
Uptime: 2 days, 02:53:59

PID USER PRI NI VIRT RES SHR S CPU% MEM% TIME+ Command
1 root 20 0 191M 9000 4096 S 0.0 0.0 0:48.11 /usr/lib/systemd/systemd --switched-root --system --deserialize 21
3778 sensu 20 0 194M 20380 2512 S 0.0 0.0 0:19.39 /opt/sensu/embedded/bin/ruby /opt/sensu/bin/sensu-client -b -c /etc/sensu/config.json -d /etc/sensu/conf.d
3780 sensu 20 0 194M 20380 2512 S 0.0 0.0 0:00.00 /opt/sensu/embedded/bin/ruby /opt/sensu/bin/sensu-client -b -c /etc/sensu/config.json -d /etc/sensu/conf.d
3590 root 20 0 250M 48520 6348 S 0.0 0.1 0:07.48 /usr/bin/ruby /usr/bin/puppet agent --no-daemonize
111415 root 20 0 250M 48520 6348 S 0.0 0.1 0:00.00 /usr/bin/ruby /usr/bin/puppet agent --no-daemonize
3460 nobody 20 0 49592 1044 668 S 0.0 0.0 0:00.01 /usr/sbin/dnsmasq --conf-file=/var/lib/libvirt/dnsmasq/default.conf --leasefile-ro --dhcp-script=/usr/libe
3461 root 20 0 49564 360 0 S 0.0 0.0 0:00.00 /usr/sbin/dnsmasq --conf-file=/var/lib/libvirt/dnsmasq/default.conf --leasefile-ro --dhcp-script=/usr/l
1956 root 20 0 89544 2132 1096 S 0.0 0.0 0:01.33 /usr/libexec/postfix/master -w

F1 Help F2 Setup F3 Search F4 Filter F5 Sorted F6 Collap F7 Nice F8 Nice + F9 Kill F10 Quit
    
```


Viewing processes (Like we did with *top* or system monitor)

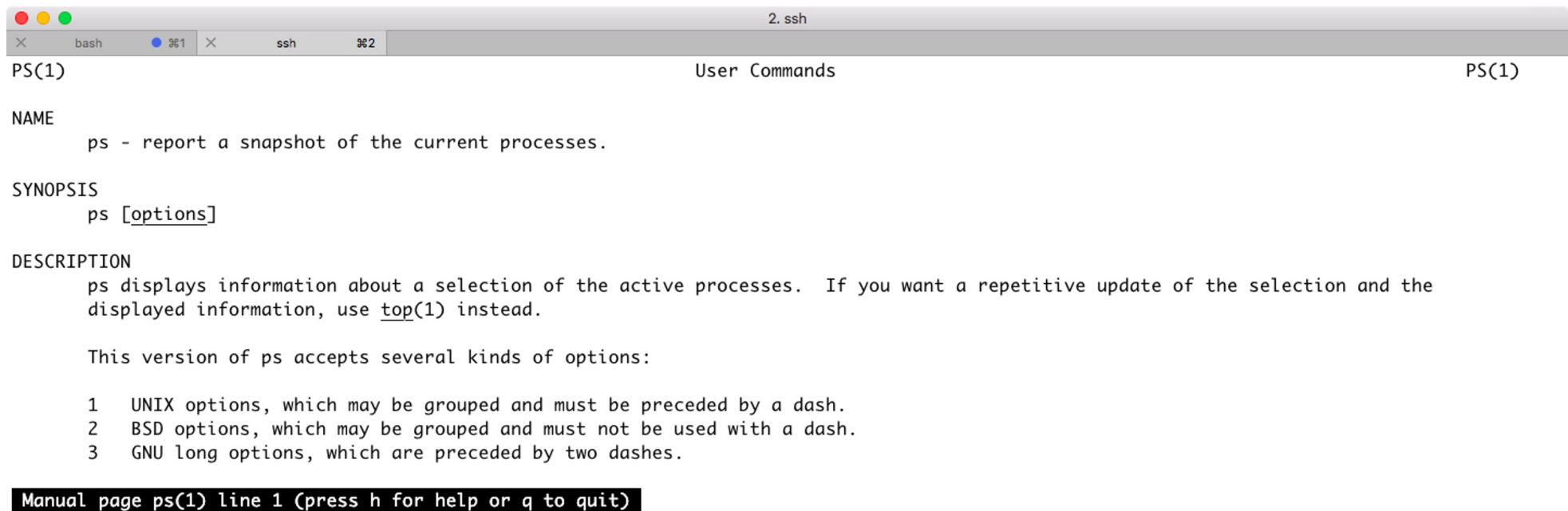
- proc itself is like a filesystem
 - (We'll talk more about everything in Unix being viewed as a file).
- We can navigate to it with `cd /proc` then list all of the processes.



```
-bash-4.2$ ls -l /proc
total 0
dr-xr-xr-x. 9 root  root      0 Oct  2 08:12 1
dr-xr-xr-x. 9 root  root      0 Oct  2 08:12 10
dr-xr-xr-x. 9 root  root      0 Oct  2 08:12 100
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1006
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1007
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1008
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1009
dr-xr-xr-x. 9 root  root      0 Oct  2 08:12 101
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1010
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1011
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 10119
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1012
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1013
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1014
dr-xr-xr-x. 9 root  root      0 Oct  2 08:13 1015
dr-xr-xr-x. 9 root  root      0 Oct  2 08:12 103
dr-xr-xr-x. 9 root  root      0 Oct  4 06:21 103599
```

man ps | Run *ps -ef*

- Another way to view actively running processes is *ps*
 - *-ef* means view all of the processes



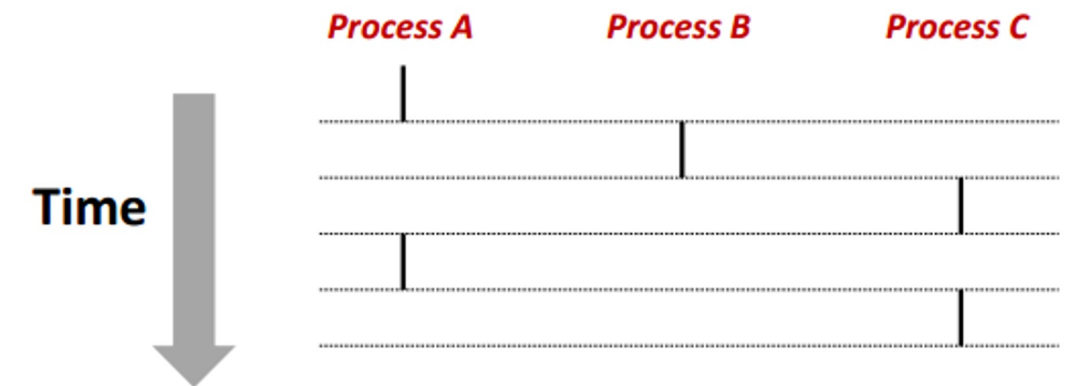
```
PS(1) User Commands PS(1)
NAME
    ps - report a snapshot of the current processes.
SYNOPSIS
    ps [options]
DESCRIPTION
    ps displays information about a selection of the active processes.  If you want a repetitive update of the selection and the
    displayed information, use top(1) instead.
    This version of ps accepts several kinds of options:
    1  UNIX options, which may be grouped and must be preceded by a dash.
    2  BSD options, which may be grouped and must not be used with a dash.
    3  GNU long options, which are preceded by two dashes.
Manual page ps(1) line 1 (press h for help or q to quit)
```


Gathering more information from proc

- We can run `cat /proc/[process id]/status` to output status information from proc
- Try some of the examples below in your environment (some may be admin restricted):
<https://www.networkworld.com/article/2693548/unix-viewing-your-processes-through-the-eyes-of-proc.html>

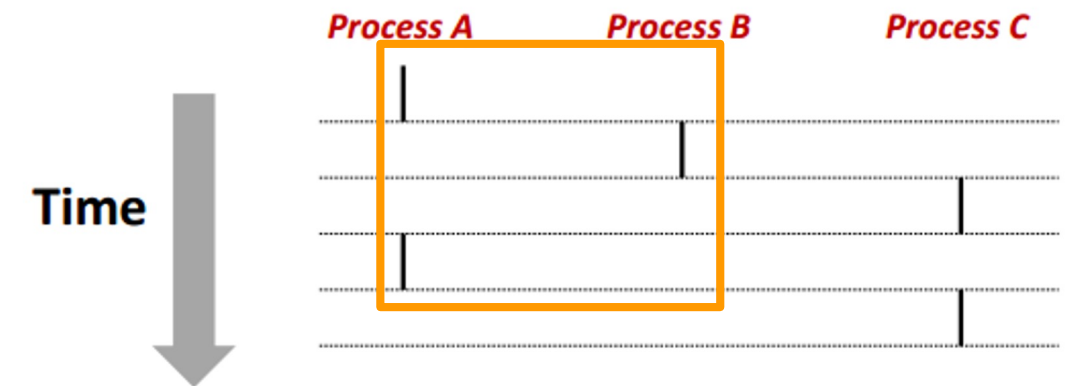
Concurrent Processing

- Each process running has its own control flow
- If they overlap in their lifetime, then they are running concurrently
 - otherwise they are sequential
- Remember only 1 process at a time can execute
 - On a single core, which processes here are concurrent to each other?
 - **Concurrent:**
 - Which are sequential?
 - **Sequential:**



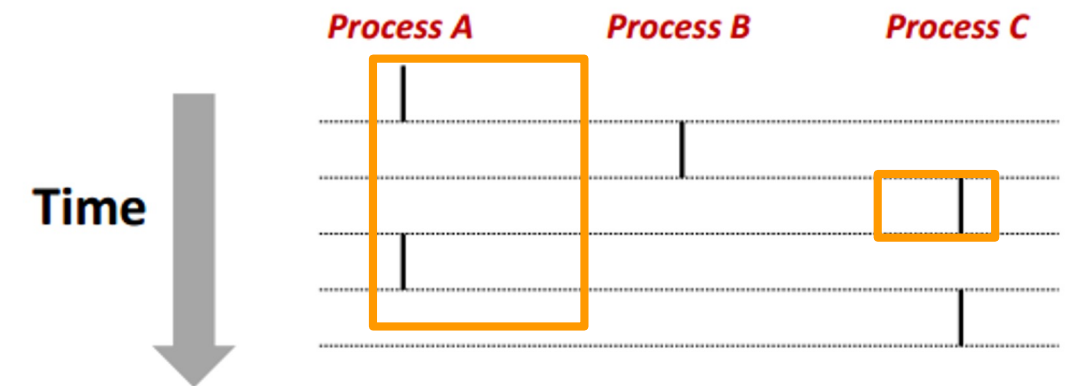
Concurrent Processing

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 - On a single core, which processes here are concurrent to each other?
 - **Concurrent:** A&B
 - Which are sequential?
 - **Sequential:**



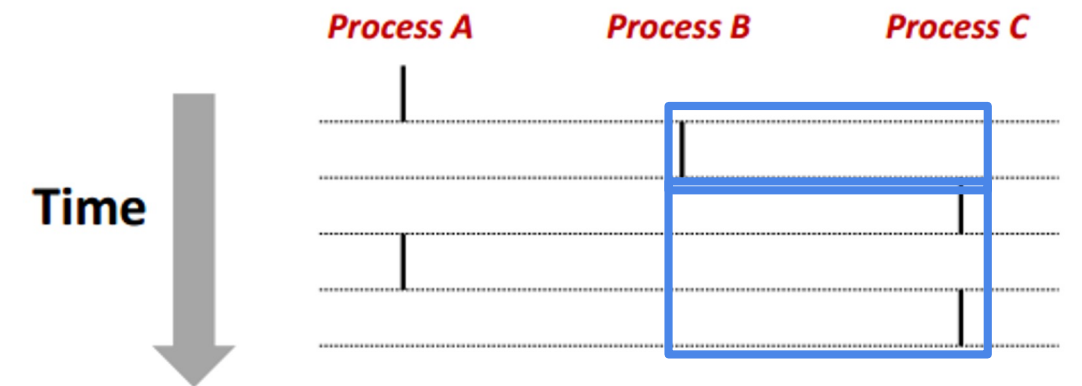
Concurrent Processing

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- If they overlap in their lifetime, then they are running concurrently
 - otherwise they are sequential
- Remember only 1 process at a time can execute
 - On a single core, which processes here are concurrent to each other?
 - **Concurrent:** A&B, A&C
 - Which are sequential?
 - **Sequential:**



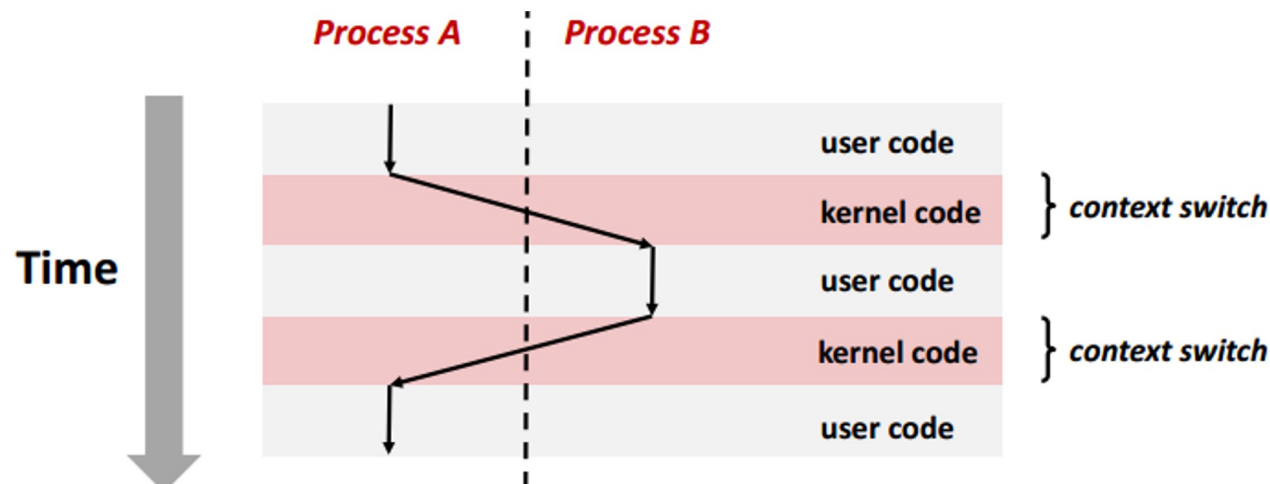
Concurrent Processing

- Each process running has its own control flow
- If they overlap in their lifetime, then they are running concurrently
 - otherwise they are sequential
- Remember only 1 process at a time can execute
 - On a single core, which processes here are concurrent to each other?
 - **Concurrent:** A&B, A&C
 - Which are sequential?
 - **Sequential:** B & C



Context Switching Illustration

- Processes are managed by a shared chunk of memory-resident OS code called the **kernel**
 - The kernel is not a separate process itself, but runs as part of other existing processes
- Context Switches pass the control flow from one process to another
 - Note how going from A to B (and B to A) requires some kernel code to be executed



Process Control

Creating a Process

- When we want to create a new process, we can do so from our parent process using the `fork()` command.
 - This creates a new child process that runs.
 - Conceptually, this new child is a **clone of itself**
- `int fork(void)`
 - **Returns 0 to the child process,
Returns child's PID to the parent process**
 - PID = process ID
 - Child is almost identical to parent
 - Child gets a copy (that is separate) to the parent's virtual address space
 - Child gets a copy of open file descriptors
 - Child has a different PID than parent.
 - Note: **Fork actually returns twice (once to the parent, and once to the child),** even though it is called once.

man fork

```
mike@mike-Lenovo-Ideapad-Y700-14ISK/proc
FORK(2)                                Linux Programmer's Manual                                FORK(2)

NAME
    fork - create a child process

SYNOPSIS
    #include <unistd.h>

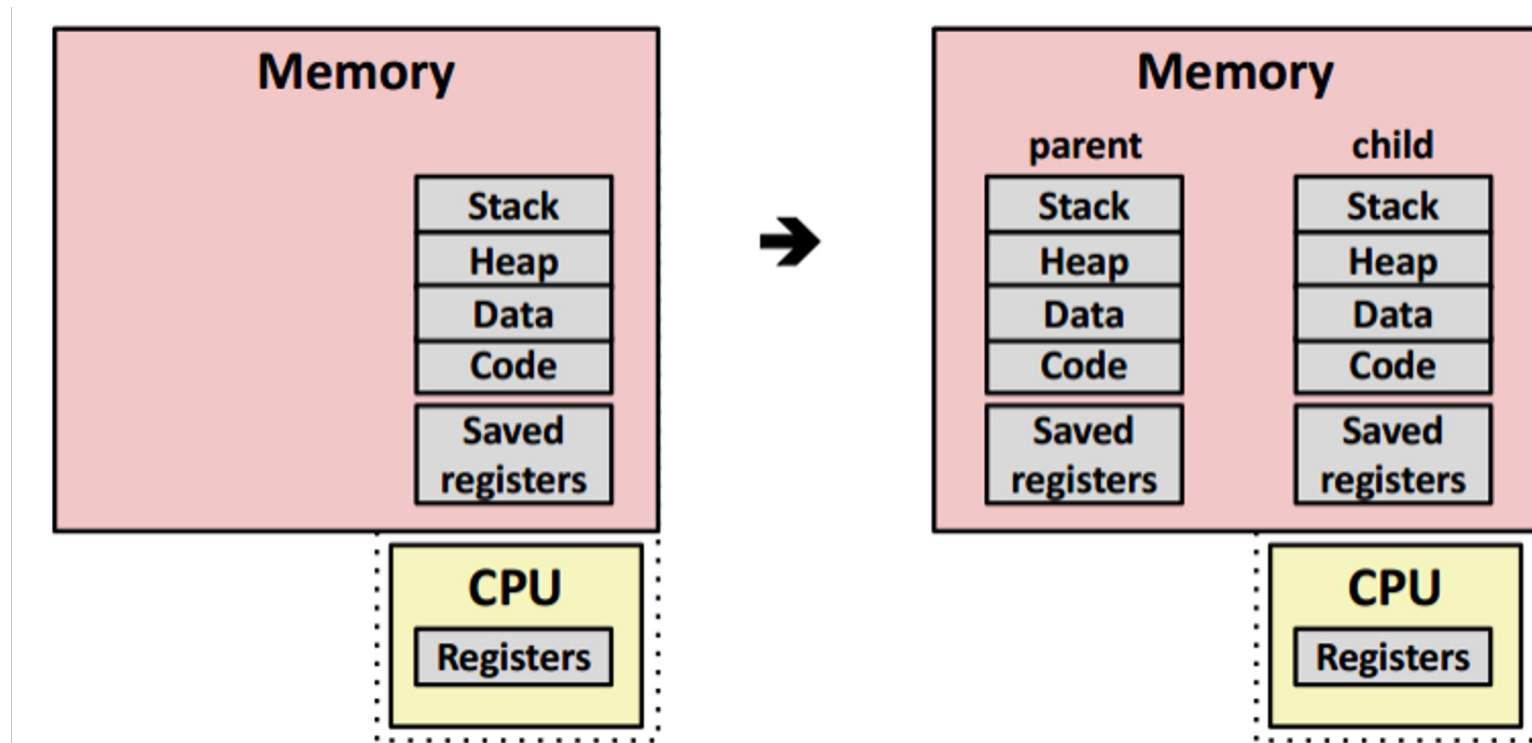
    pid_t fork(void);

DESCRIPTION
    fork() creates a new process by duplicating the calling process. The new
    process is referred to as the child process. The calling process is referred to
    as the parent process.

    The child process and the parent process run in separate memory spaces. At the
    time of fork() both memory spaces have the same content. Memory writes, file
    mappings (mmap(2)), and unmappings (munmap(2)) performed by one of the processes
    do not affect the other.

Manual page fork(2) line 1 (press h for help or q to quit)
```

Conceptual View of fork() | The before and after



Additional Process commands

- `int exec(const char *pathname, char *argv[], ...)`
 - System call to change the program being run by the current process
- `wait()` – system call to wait for a process to finish
- `signal()` – system call to send a notification to another process

- `pid_t getpid(void)`
 - Return PID of the current process
- `pid_t getppid(void)`
 - Returns PID of parent process
- Note that when we create a process with `fork`
 - The parent child relationship, makes a tree.
- (Note [pid_t](#) is a signed integer)

UNIX Process Management

Inherits most attributes from the parent.

Differences:
Register values including PC, address space, etc.
and **return value from fork()**

Child Process

```
pid = fork();  
if (pid == 0)  
    exec(...);  
else  
    ...
```

```
main() {  
    ...  
}
```

pid = 0

pid = 9418

```
pid = fork();  
if (pid == 0)  
    exec(...);  
else  
    ...
```

```
pid = fork();  
if (pid == 0)  
    exec(...);  
else  
    ...
```

Original Process

Question: What does this code print?

```
int child_pid = fork();  
if (child_pid == 0) {           // I'm the child process  
    printf("I am process # %d\n", getpid());  
    return 0;  
} else {                       // I'm the parent process  
    printf("I am parent of process # %d\n", child_pid);  
    return 0;  
}
```

Process State

- When our process is running, it may be in one of the states below
 - Running
 - Ready
 - Blocked
- Terminated
 - Process is stopped permanently

Process Termination

- Process may be terminated for 3 reasons
 - Receives a signal to terminate
 - Returns from main routine
(what we have normally been doing in the class)
 - Calling the exit function
 - Terminates with a given status
 - Returning 0 means no error
 - When exit is called, this only happens once, and it does not return
 - Note that if we have an error in our system, sometimes we do not want to exit right away (e.g. safety critical system)

Process Termination

- Typically, a process will `wait(pid)` until its child process(es) complete
 - You will learn about zombie and orphaned processes in the lab
- `abort(pid)` can be used to immediately end a child process